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In[1]:= (* Algebra of 2x2 traceless matrices *)
In[2]:= SetDirectory[NotebookDirectory[]];
In[3]:= << "SymbolLie.wl"
SymbolLie (v. 1.6) - A Package for determining Optimal Systems of Lie Subalgebras.

In[4]:= e1 = {{1, 0}, {0, -1}};
In[5]:= e2 = {{0, 1}, {0, 0}};
In[6]:= e3 = {{0, 0}, {1, 0}};
In[7]:= cs = StructureConstants[{e1, e2, e3}, {}]
Out[7]= {{{0, 0, 0}, {0, 0, 1}, {0, -1, 0}}, {{0, 2, 0}, {-2, 0, 0}, {0, 0, 0}}, {{0, 0, -2}, {0, 0, 0}, {2, 0, 0}}}

In[8]:= ct = CommutatorTable[cs]; ct // MatrixForm
Out[8]//MatrixForm=

$$\begin{pmatrix} 0 & 2 \Xi_2 & -2 \Xi_3 \\ -2 \Xi_2 & 0 & \Xi_1 \\ 2 \Xi_3 & -\Xi_1 & 0 \end{pmatrix}$$


In[9]:= Timing[alg1 = SubAlgebra[cs, {}, {}, 1]];
There are 7 1-D families of subalgebras to be analyzed.
Done.
Out[9]= {0.491847, Null}

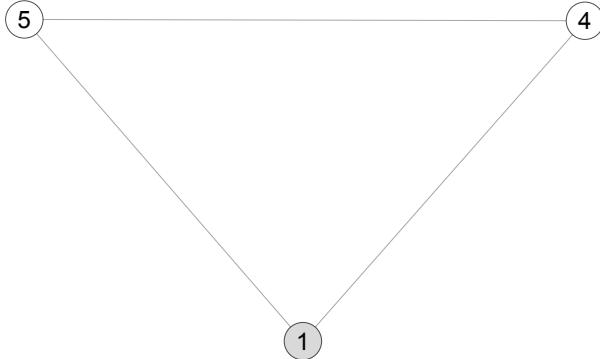
In[10]:= Timing[alg2 = SubAlgebra[cs, {}, {}, 2]];
There are 2 2-D families of subalgebras to be analyzed.
Done.
Out[10]= {0.313494, Null}

In[11]:= PrintOptimal[alg1]
There are 3 optimal families of 1-dimensional Lie subalgebras.
Out[11]= {{\Xi_1}, {\Xi_2}, {\Xi_2 + \alpha_1 \Xi_3}}

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In[12]:= PrintGraph[alg1, 1]
{1 → {E1}, 2 → {E2}, 3 → {E3}, 4 → {E1 + α1 E2},
5 → {E1 + α1 E3}, 6 → {E2 + α1 E3}, 7 → {E1 + α1 E2 + α2 E3}}
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Out[12]=



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In[13]:= PrintOptimal[alg2]
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There are 1 optimal families of 2-dimensional Lie subalgebras.

Out[13]=

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{ {E1, E2} }
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In[14]:= PrintGraph[alg2, 1]
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{1 → {E1, E2}, 2 → {E1, E3}}
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Out[14]=



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In[15]:= alg = {alg1, alg2}
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Out[15]=

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{ {{ {1, 0, 0, 1, 1, 0, 0},
{0, 1, 1, 0, 0, 0, 0}, {0, 1, 1, 0, 0, 0, 0}, {1, 0, 0, 1, 1, 0, 0},
{1, 0, 0, 1, 1, 0, 0}, {0, 0, 0, 0, 0, 1, 1}, {0, 0, 0, 0, 0, 1, 1}},
{{1}, {2}, {4}, {3}, {5}, {6}, {7}}, {{0, 0, 0}, {0, 0, 1}, {0, -1, 0}},
{{0, 2, 0}, {-2, 0, 0}, {0, 0, 0}}, {{0, 0, -2}, {0, 0, 0}, {2, 0, 0}}},
{{{1, 1}, {1, 1}}, {{1, 2}, {1, 4}}, {{0, 0, 0}, {0, 0, 1}, {0, -1, 0}},
{{0, 2, 0}, {-2, 0, 0}, {0, 0, 0}}, {{0, 0, -2}, {0, 0, 0}, {2, 0, 0}}}}
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In[16]:= SessionTime[]
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Out[16]=

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4.875243
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