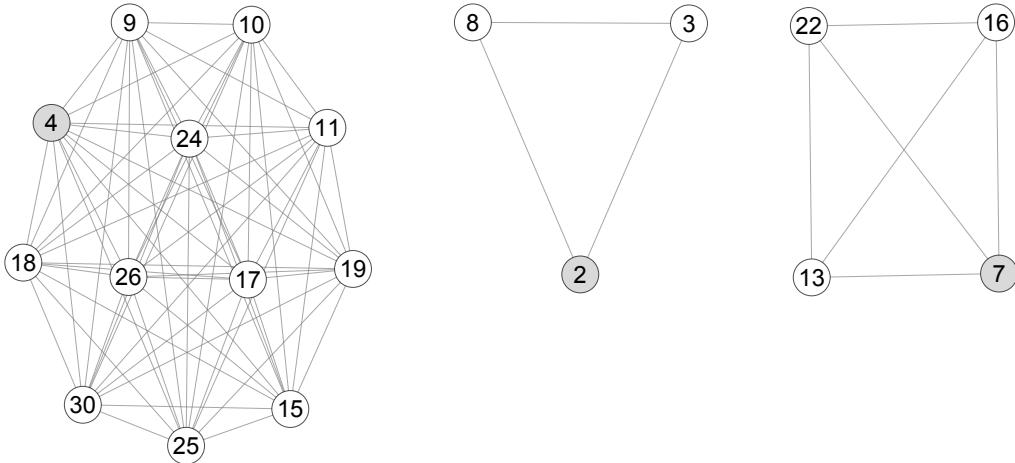


Algebra of Lie symmetries of viscous Burgers' equation

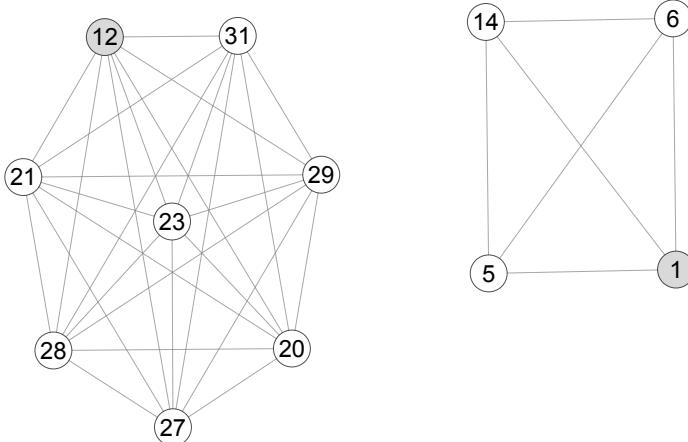
```
In[1]:= SetDirectory[NotebookDirectory[]];  
  
In[2]:= << "SymbolLie.wl"  
SymbolLie (v. 1.6) - A Package for determining Optimal Systems of Lie Subalgebras.  
  
In[3]:= gens = {{1, 0, 0}, {0, 1, 0}, {0, t, 1}, {2 t, x, -u}, {t^2, t x, x - t u}};  
vars = {t, x, u};  
pars = {{}, {}};  
  
In[4]:= cs = StructureConstants[gens, vars];  
  
In[5]:= CommutatorTable[cs] // MatrixForm  
Out[5]//MatrixForm= 
$$\begin{pmatrix} 0 & 0 & \Xi_2 & 2\Xi_1 & \Xi_4 \\ 0 & 0 & 0 & \Xi_2 & \Xi_3 \\ -\Xi_2 & 0 & 0 & -\Xi_3 & 0 \\ -2\Xi_1 & -\Xi_2 & \Xi_3 & 0 & 2\Xi_5 \\ -\Xi_4 & -\Xi_3 & 0 & -2\Xi_5 & 0 \end{pmatrix}$$
  
  
In[6]:= Timing[alg1 = SubAlgebra[cs, pars, 1];]  
There are 31 1-D families of subalgebras to be analyzed.  
Done.  
Out[6]= {24.8638, Null}  
  
In[7]:= PrintOptimal[alg1]  
There are 5 optimal families of 1-dimensional Lie subalgebras.  
Out[7]= {{\Xi_1}, {\Xi_2}, {\Xi_4}, {\Xi_1 + \alpha_1 \Xi_3}, {\Xi_1 + \alpha_1 \Xi_5}}
```

```
In[8]:= PrintGraph[alg1, 1]
```

```
{1 → {E1}, 2 → {E2}, 3 → {E3}, 4 → {E4}, 5 → {E5}, 6 → {E1 + α1 E2}, 7 → {E1 + α1 E3},
8 → {E2 + α1 E3}, 9 → {E1 + α1 E4}, 10 → {E2 + α1 E4}, 11 → {E3 + α1 E4}, 12 → {E1 + α1 E5},
13 → {E2 + α1 E5}, 14 → {E3 + α1 E5}, 15 → {E4 + α1 E5}, 16 → {E1 + α1 E2 + α1 E3},
17 → {E1 + α1 E2 + α2 E4}, 18 → {E1 + α1 E3 + α1 E4}, 19 → {E2 + α1 E3 + α2 E4}, 20 → {E1 + α1 E2 + α1 E5},
21 → {E1 + α1 E3 + α1 E5}, 22 → {E2 + α1 E3 + α1 E5}, 23 → {E1 + α1 E4 + α2 E5},
24 → {E2 + α1 E4 + α1 E5}, 25 → {E3 + α1 E4 + α2 E5}, 26 → {E1 + α1 E2 + α2 E3 + α1 E4},
27 → {E1 + α1 E2 + α2 E3 + α1 E5}, 28 → {E1 + α1 E2 + α2 E4 + α1 E5}, 29 → {E1 + α1 E3 + α2 E4 + α1 E5},
30 → {E2 + α1 E3 + α2 E4 + α3 E5}, 31 → {E1 + α1 E2 + α2 E3 + α3 E4 + α1 E5}}
```



```
Out[8]=
```



```
In[9]:= Timing[alg2 = SubAlgebra[cs, pars, 2];]
```

There are 17 2-D families of subalgebras to be analyzed.

Done.

```
Out[9]= {128.3, Null}
```

```
In[10]:= PrintOptimal[alg2]
```

There are 5 optimal families of 2-dimensional Lie subalgebras.

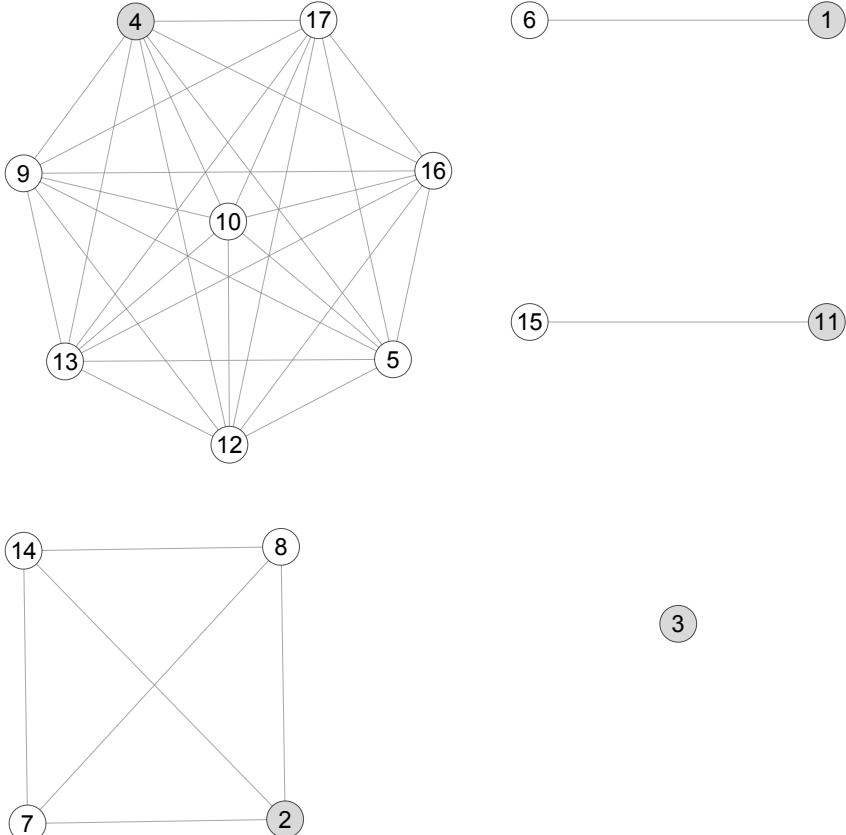
```
Out[10]=
```

```
{ {E1, E2}, {E1, E4}, {E2, E3}, {E2, E4}, {E1 + α1 E3, E2} }
```

```
In[11]:= PrintGraph[alg2, 1]
```

```
{1 → {E1, E2}, 2 → {E1, E4}, 3 → {E2, E3}, 4 → {E2, E4}, 5 → {E3, E4}, 6 → {E3, E5},  
7 → {E4, E5}, 8 → {E1, E2 + α1 E4}, 9 → {E2, E3 + α1 E4}, 10 → {E3, E4 + α1 E5},  
11 → {E1 + α1 E3, E2}, 12 → {E1 + α1 E4, E2}, 13 → {E2 + α1 E4, E3}, 14 → {E3 + α1 E4, E5},  
15 → {E2 + α1 E5, E3}, 16 → {E1 + α1 E3 + α2 E4, E2}, 17 → {E2 + α1 E4 + α2 E5, E3}}
```

```
Out[11]=
```



```
In[12]:= Timing[alg3 = SubAlgebra[cs, pars, 3];]
```

There are 12 3-D families of subalgebras to be analyzed.

Done.

```
Out[12]=
```

```
{959.884, Null}
```

```
In[13]:= PrintOptimal[alg3]
```

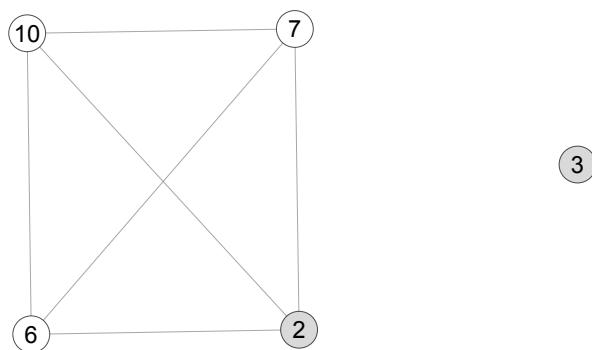
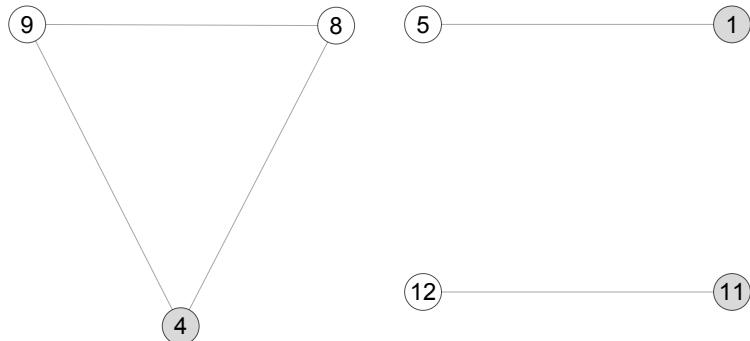
There are 5 optimal families of 3-dimensional Lie subalgebras.

```
Out[13]=
```

```
{ {E1, E2, E3}, {E1, E2, E4}, {E1, E4, E5}, {E2, E3, E4}, {E1 + α1 E5, E2, E3} }
```

```
In[14]:= PrintGraph[alg3, 1]
{1 → {E1, E2, E3}, 2 → {E1, E2, E4}, 3 → {E1, E4, E5}, 4 → {E2, E3, E4}, 5 → {E2, E3, E5},
6 → {E3, E4, E5}, 7 → {E1, E2, E3 + α1 E4}, 8 → {E2, E3, E4 + α1 E5}, 9 → {E1 + α1 E4, E2, E3},
10 → {E2 + α1 E4, E3, E5}, 11 → {E1 + α1 E5, E2, E3}, 12 → {E1 + α1 E4 + α2 E5, E2, E3}}
```

Out[14]=



```
In[15]:= Timing[alg4 = SubAlgebra[cs, pars, 4];]
There are 2 4-D families of subalgebras to be analyzed.
```

Done.

Out[15]=

{120.888, Null}

```
In[16]:= PrintOptimal[alg4]
There are 1 optimal families of 4-dimensional Lie subalgebras.
```

Out[16]=

{ {E1, E2, E3, E4} }

```
In[17]:= PrintGraph[alg4, 1]
{1 → {E1, E2, E3, E4}, 2 → {E2, E3, E4, E5}}
```

Out[17]=



```
In[18]:= alg = {alg1, alg2, alg3, alg4}
Out[18]=
```

```
{ {{{1, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 1, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0}, {0, 1, 1, 0, 0, 0, 0, 1,
```



```
{0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}, {-1, 0, 0, 0, 0}}, {{0, 0, 0, 0, 0},  
{0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}, {0, 0, 0, 0, 2}, {0, 0, 0, -2, 0}}}}}
```

```
In[19]:= SessionTime[]
```

```
Out[19]=
```

```
1190.357148
```